



PRŮVODNÍ DOKUMENTACE ACCOMPANYING DOCUMENTATION

D0109.PD.01

ELECTRIC MOTOR DRIVE MECHANISM

for a switching device used outdoors on traction current lines (Austrian Railways)

TYPE SUP-A

ISO 9001:2009 ISO 14001:2005 OHSAS 18001:2008



USE

The SUP-A type electric motor drive mechanism is intended to be used in dependent machinery systems to control switching devices mounted outdoors, such as medium voltage disconnectors, switch disconnectors and earthing switches. It can be used as a means for local, remote and emergency control of the switching device. The values of output torque provide for adequate switching reliability, even in heavy duty operating conditions. The drive mechanism features a simple and reliable design with only minor demands on maintenance.

The drive mechanism is designed in a way to achieve the switching device's end positions with adequate reliability while sending out positive signals about the ON and OFF switching positions.

STANDARDS AND REGULATIONS

The SUP electric motor drive mechanism meets the requirements of the following standards: ČSN EN 62271-103; ČSN EN 62271-1; ČSN EN 61439-1

MAIN TECHNICAL PARAMETERS

Type of used cabinet SUS 1 (IVEP, a.s. manufacturer)

Protection degree (of closed drive mechanism) IP 55 Covering of inner doors IP 30 Mechanical toughness IK 07

Protection against direct touch connecting all metal parts together

Weight approx. 60 kg

(depending on the type and equipment level)

Output torque – rated value 76 Nm
Output torque – highest value 240 Nm
Min. forces in rod 2150 N

Max. forces in rod 2150 N 10000 N

Cycle duration breaking operation: 1.5 s making operation: 1.5 s

Working angle 185° (adjusted at the manufacturer's shop)

Minimum control impulse 0.15

Range of control voltages 0.85 to 1.1 x Un

Rated insulation voltage Ui 300V, 50Hz

Rated voltage Un

Rated withstand impulse voltage Uimp

1,5kV

Motor drive control voltage 230V AC, 50Hz
Motor drive power supply voltage 230V AC, 50Hz
Motor type DAGU, 220V DC, 300W

Rated cabinet current Inc 4A

Rated suspended short-circuit current lcc 10kA (external protection)

Ambient temperature - 25°C to + 40°C (without heating)

Maximum ambient humidity 50%

Mechanical service life 20000 C-O cycles operations or 3 to 5 years

2

Input opening for the insertion of cables 2 x M 32x1,5; 2 x M 25x1,5

Cross section of connecting conductor 1 connecting conductor

solid wire 0.5...4 mm² stranded wire 1.5...4 mm² stranded wire with ferrule 0.5...2.5 mm²

Tightening torque of connecting terminals 0.4...0.6 Nm (M2.5)

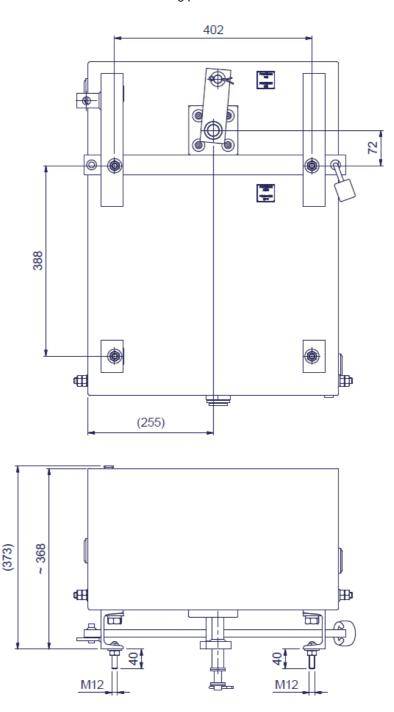
Mounting possibility wall or pole mounting

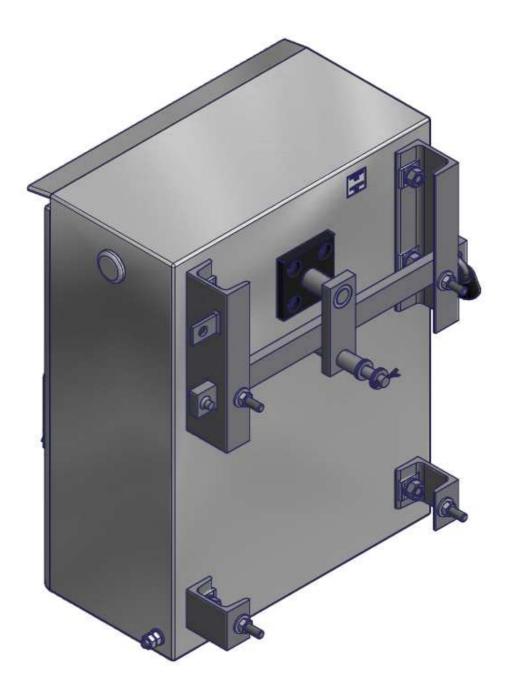
INSTALLATION OF THE DRIVE MECHANISM

The proper functioning necessitates to have the electric motor drive mechanism mounted onto a stable supporting structure of adequate carrying capacity. The installation (Fig. 1) can be accomplished in two ways: option (variant) 1 is used for mounting the device on a pole, option (variant) 2 serves for mounting the device on a supporting steel structure. The fixing is done using four M12 screws. The tightening torque values – see Table 1.

Fig. 1

Mounting points location





The main shaft of the drive mechanism (Fig. 2 – item 1) carries a control handle installed at the manufacturer's (Fig. 2 – item 2). The drive stroke (travel) attains 200 mm. A pull rod hooked up on the controlled switching device is fixed to the control handle journal (Fig. 2 – item 3). The pull rod needs to be preloaded in order to ensure the proper functioning of the drive mechanism and of the whole assembly, and to attain the ON switching end position. The adjustment procedure of the whole assembly is not a subject of this manual.

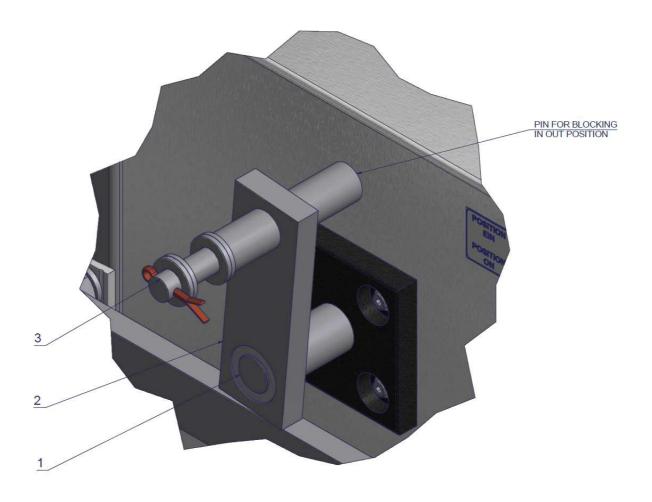


Table 1

Table with specified torque values

Screw size	Tightening torque (Nm)
M4	2.5
M6	9
M8	22
M10	45
M12	75
M16	180

- Terminal boards X1 and X2 mounted in the inside of the cabinet serve to connect the power supply, control and indication voltages (Fig. 3, item 1)
- Cables enter into the cabinet from the bottom side via 2pcs of M 32x1,5 bushing and via 2pcs M 25x1,5 bushing.
- Grounding is to be connected to the cabinet from both sides, to the M12 terminals (Fig. 4).

Fig. 3

Cabinet internal wiring; layout

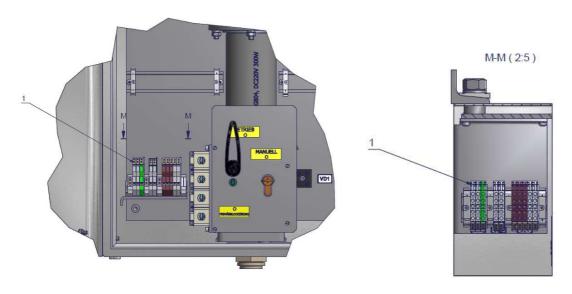
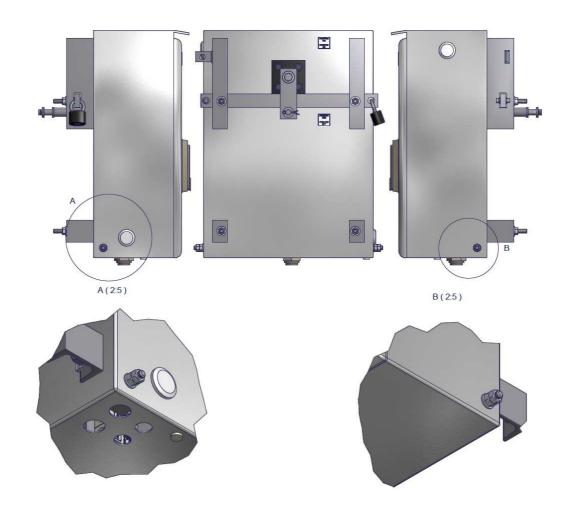


Fig. 4

Location of cabinet grounding points



TYPE DESIGNATION OF THE ELECTRIC MOTOR DRIVE UNIT

Table 1

Design	Electric drive	Rated voltage of motor (V)	Motor power output (W)	Rated current (A)	Highest current (A)	Rated output torque (Nm)	Highest breakaway torque (Nm)
SUP-A-HF 50-80	DAGU MG804.1	230 V AC, 50 Hz	300	2,0	8,0	76	240

Note:

Rated current flows through the motor during ordinary operating conditions (rated torque) Highest current denotes the peak value of starting current

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OPERATING CONDITIONS

The electric motor drive mechanisms are envisaged to be used in common outdoor and indoor operating environments as defined by the ČSN EN 60694 standard, part 2.

DESCRIPTION, FUNCTION

The SUP -A-HF 50-80... electric motor drive mechanism consists of subassemblies such as the cabinet and a panel with the drive unit (see Fig. 5). The figure shows a drive mechanism with opened external door.

The external door does not incorporate any locking mechanism and its purpose is only to protect the drive mechanism from atmospheric influences. The internal door (panel) comprises the switching position indicator and the changeover lever for setting the respective operating modes, completed with a locking mechanism. The lever can be secured in any switching position with a key, to prevent it from tampering.

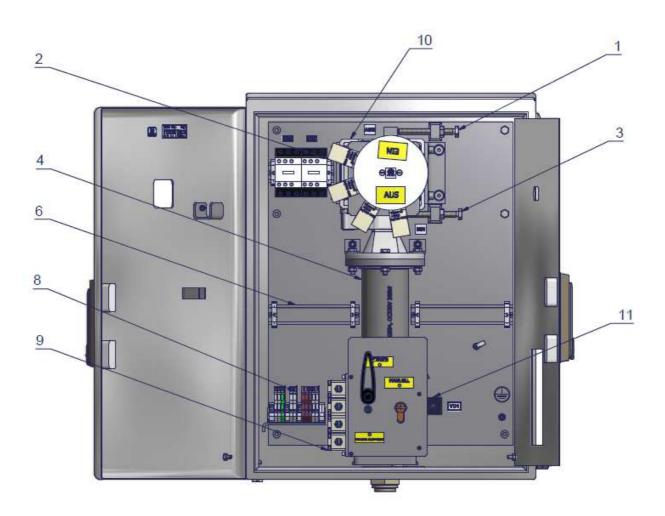
Fig. 5

Cabinet of drive mechanism, with opened outside door



- 1 Cabinet of drive mechanism external door
- 2 Cabinet of drive mechanism internal door
- 3 Internal door handle with lock
- 4 External door handle with lock
- 5 Indicator of drive switching position
- 6 Venting louvers
- 7 Lever to control the drive operation modes
- 8 Control lever lock
- 9 Earthing screw (terminal)

- 10 Entry for control cables
- 11 Draining plug
- 12 Blocking rod
- 13 Padlock
- 14 Eye for blocking rod
- 15 Entry for emergency control

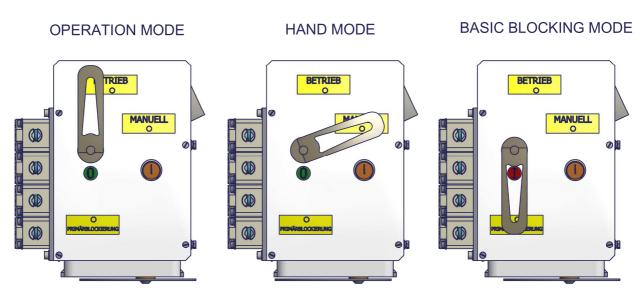


- 1 Mechanical stop OFF switching position
- 2 End switches for control of motor and indication
- 3 Mechanical stop ON switching position
- 4 Electric motor
- 5 Contactors of electric motor
- 6 Removable free DIN rail approx..150mm lengthy
- 7 Auxiliary terminal board
- 8 X1 and X2 Main terminal boards
- 9 End switches of internal door
- 10 Gearbox
- 11 Rectifier
- 12 Blocking and changeover mechanism

The wiring diagram of the electric motor drive mechanism is shown in the appendix (Fig. 9). With manual handle of the drive operation mode changeover switch (Fig. 6) in position BETRIEB (= OPERATION) the drive mechanism can be remotely controlled in all its functions. In the MANUELL (=MANUAL) position the sliding block guide of the blocking mechanism is displaced which makes it possible to insert the operating handle of emergency manual control into the drive cabinet from the bottom. The insertion of the handle disables the remotely controlled motor-actuated operation of the switching device as a means to protect the operating staff.

In the PRIMÄRBLOCKIERUNG (= ELECTRICAL AND MECHANICAL CONTROL BLOCKING) position of the changeover switch the power connection to the electric motor is broken and, at the same time, the shaft is blocked mechanically.

MODE SELECTION



MANUAL EMERGENCY CONTROL

In emergency situations the drive mechanism can be operated manually using a manual handle slipped in over the hexagonal end of the motor shaft after the removal of a cover on the bottom side of the drive (Fig. 5, item 10), and after putting the changeover switch into "MANUAL" position. When slipping the handle an end switch in the power circuit of the motor becomes opened still before the hexagonal shaft end has been reached by the handle, which is a protective measure to protect the staff in case of faulty handling.

Caution! The system of emergency manual control of the drive mechanism under load serves only to control the switching device in emergency situations. It is not allowed to finish the handling process in an interim position and, if such happens, it is necessary to complete the handling process as soon as possible, using the highest possible speed of the movement. Devices without load can be operated with any arbitrary speed, and the movement can be stopped at any moment chosen. The operating staff is strongly discouraged to use the system of emergency control for switching the device ON and OFF under load.

MAINTENANCE RULES

The SUP-A-HF 50-80... electric motor drive mechanism poses only minimum demands on the maintenance. The gearbox is filled with solid grease and does not require any topping up or checks over the whole service life i.e. 30 years or 50 000 C-O switching operations.

It is recommended to perform annual inspection of the drive, in the course of which the following items are being checked:

- verification whether the end switching positions are achieved by the drive mechanism
- visual inspection of surface damages and obvious defects both in the inside and outside of the cabinet
- excessive noise, etc.

FIG. 7 - SWITCH DISCONNECTOR WITH THE SUP ELECTRIC MOTOR DRIVE MECHANISM ASSEMBLED STATE

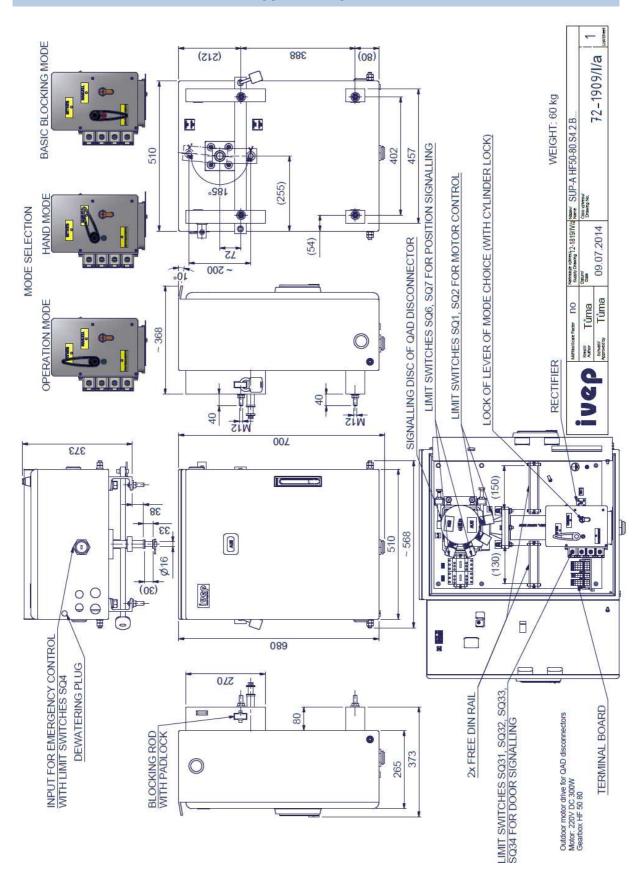


FIG. 8 – SWITCH DISCONNECTOR WITH THE SUP ELECTRIC MOTOR DRIVE MECHANISM ASSEMBLED STATE

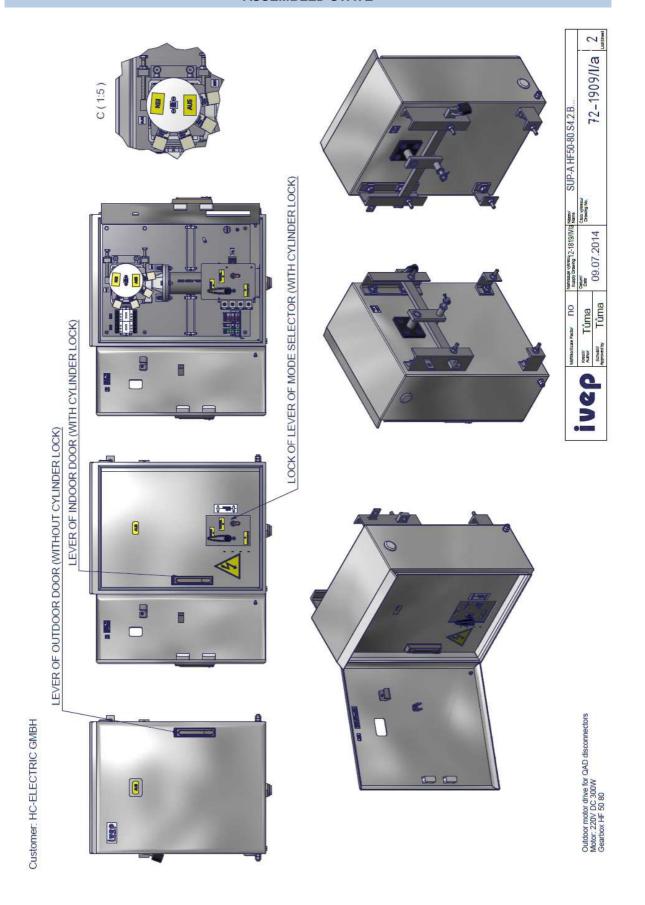
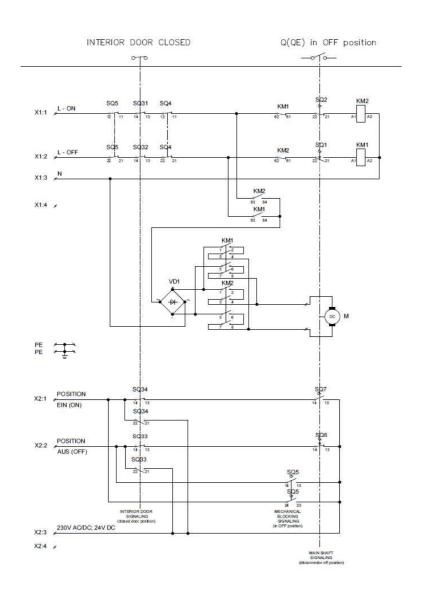


FIG. 9 - WIRING DIAGRAM OF THE SUP DRIVE MECHANISM



Limit switch (FR515: 1NO 1NC) - OFF POSITION Limit switch (FR515: 1NO 1NC) - ON POSITION SQ2

VD1 RECTIFIER (KBPC2506 - usm. måstek 250V/600V I=25A)

TERMINAL BLOCK 2x WK 4 E/U, 1x WK4 E SL/U TERMINAL BLOCK 2x WK 4 E/U X2

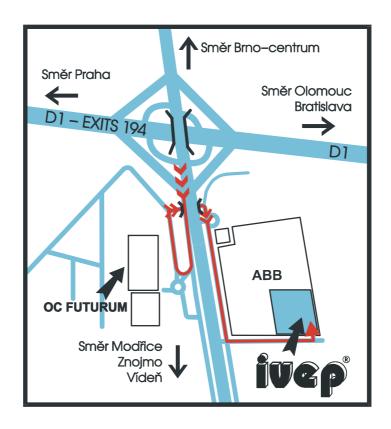
ASSEMBLING AUXILIARY TERMINAL BLOCK 3x WK4 E/U/VB,

2x WK 4 E/U

motor 220V DC 300W KM1, KM2 contactors (control voltage 230V AC)

SQ1, SQ8 - pressed down in position AUS SQ2, SQ7 - pressed down in position EIM SQ5, SQ7 - pressed down in position EIM SQ6 (FR117) - pressed down in position MANUELL and PRIMARBLOCKIERUNG SQ5 (FR215) - pressed down only in position PRIMARBLOCKIERUNG

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					SUP-A V2 outdoor drive			1 L
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 $Sm\check{e}r = direction$

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